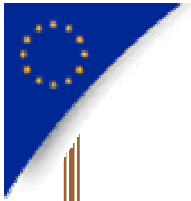


WP6: Development of the FDI System

(UNAM, LBE, SPES)

November 2003 - November 2004

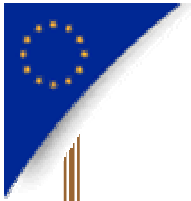




WP6: Objectives

- **O6.1** To develop an efficient FDI system for biological aerobic batch systems
- **O6.2** To test & validate such a system in simulation using the NL models developed within by WP2
- **O6.3** To integrate the FDS within a higher decision level (supervision system WP7)
- **O6.4** To test the global system at lab-scale in the presence of fault WP1
- **O6.5** To validate the monitoring system with a field-scale pilot plant WP1

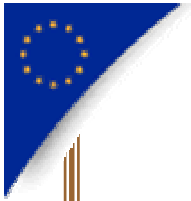




WP6: Deliverables

- **D6.1** Diagnosis algorithms for robustly detecting and isolating of a number of sensors, actuators or/and process faults for SBR (T0+27)
- **D6.2** User guide of the FDI system which helps the operator of the reactor to reconfigure the process in abnormal conditions (T0+30)

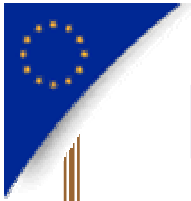




WP6: Milestones & Expected Results

- **M6.1** Specifications of a diagnosis system for SBR considering practical situations: T0+16
- **M6.2** A set of validated (simulation) FDI routines which guaranty the protection of the biomass in the SBR: T0+16
- **M6.3** Validation of the diagnosis algorithms at field scale pilot plant and tuning of the system before integration: T0+27

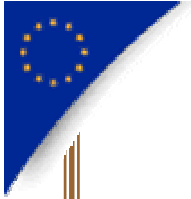




Previous Works [11.03 – 04.04]

- Specification of devices and fault cases, **M6.1**
 - Sensor: Deterioration in the DO membrane
 - Actuator: Flow Valve
 - **Process**: Reduction in the nitratisation capacity. POLIMI
- Proposition of a distribution system for FDI tasks, **M6.2**
 - Two levels in the diagnosis systems
- Starting the design of FD routines for the DO, **M6.2**
 - The parameters associated to the diffusion in the membrane is automatic identified



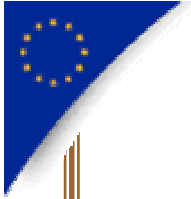


WP6: Activity Report

April 04- November 04

UNAM: C Verde, D Wimberger, J Mina & J Cuellar





Progress towards achieving objectives

- 90% Validation by simulation of the FD algorithm for the DO, **D6.1** & **M6.2**
- 30% Methodology to design the FD for the servo-valve, **D6.1** & **M6.2**

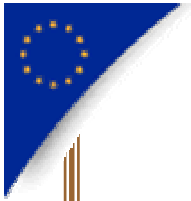




Progress towards achieving objectives

- **Process Cases D6.1**
 - 100% Analysis of the applicability of EM2a Model for FD task **O6.1&O6.2**
 - 60% Introduction of a reactor monitoring system using only DO data and specific short cycles for identification **M6.2**
 - 20% Develop of a descriptive model which can be used for PF tasks **O6.1&O6.2**

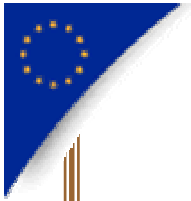




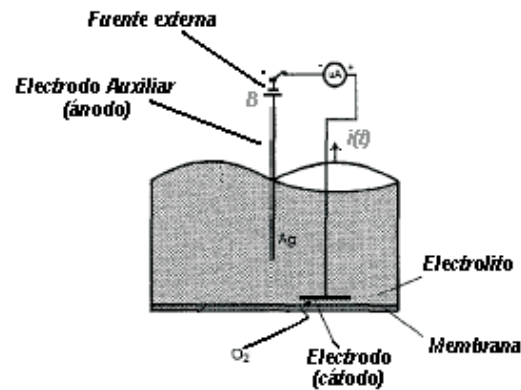
Future Activities

- **D6.1.** Develop of a descriptive model which can be tackled in the framework of FDI task
- **M6.2.** Develop of FDI algorithm for a Valve based on pattern recognition
- **M6.3.** Validation of the whole monitoring system
- **M6.2** a sensor FDI module is under development in conjunction with the extension of the SUS of WP7.





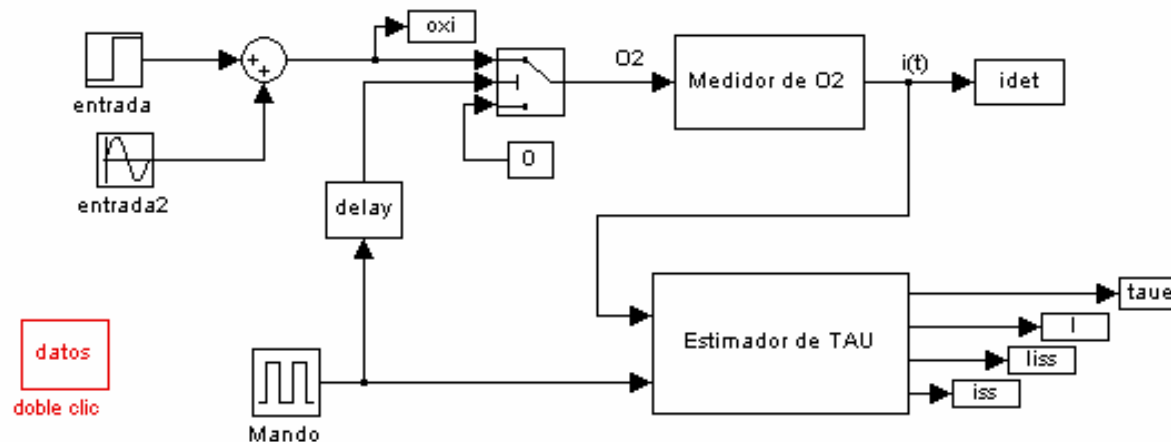
FD algorithm for DO

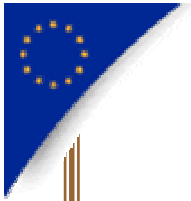


$$i(t) = i_{\infty} \left(1 + 2 \sum_{n=1}^{\infty} \exp\left(-\frac{(n\pi)^2 D_m t}{b^2}\right) \right)$$

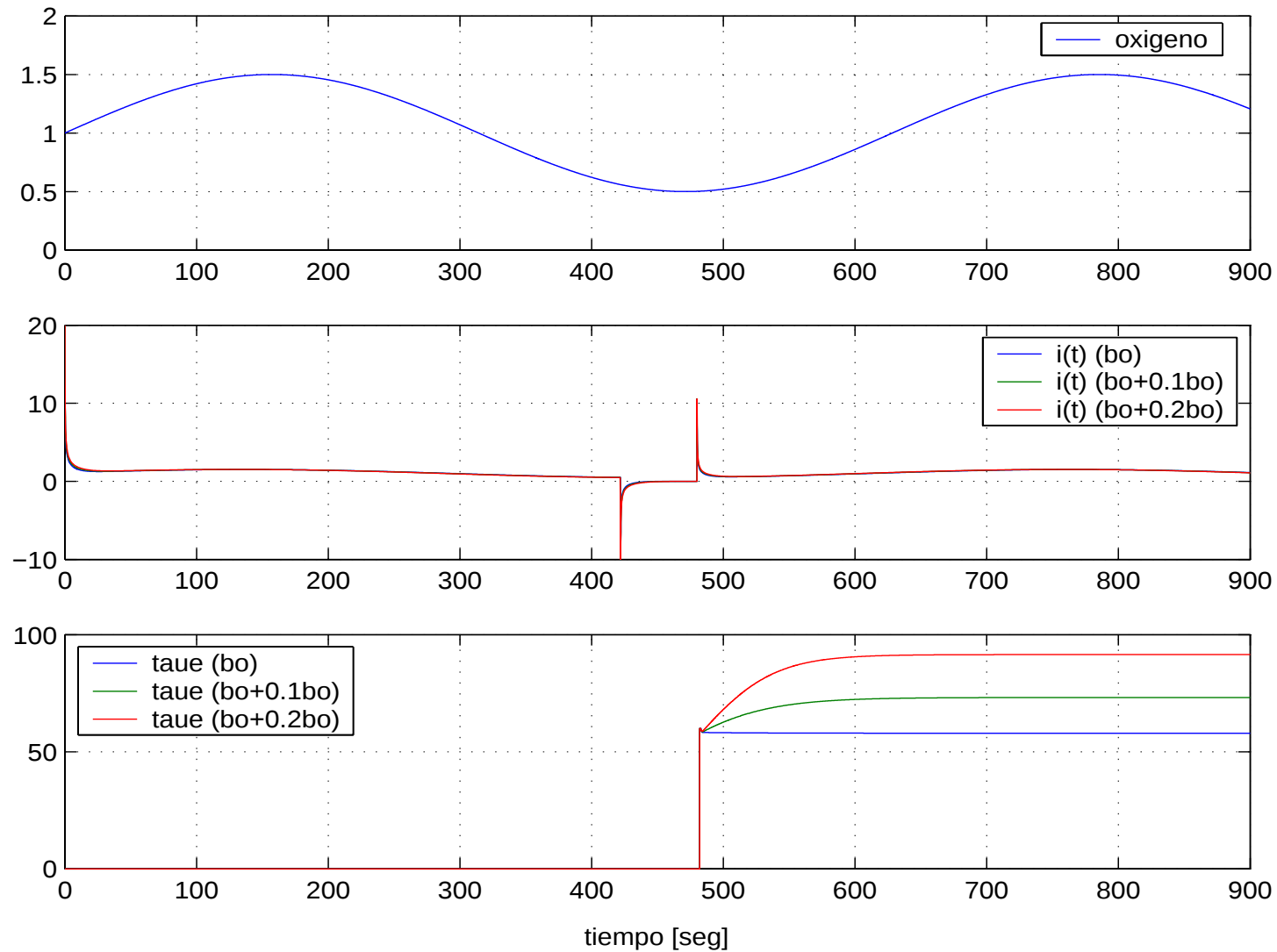
$D_m =$

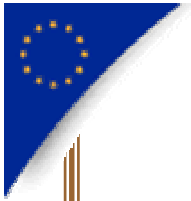
$b =$



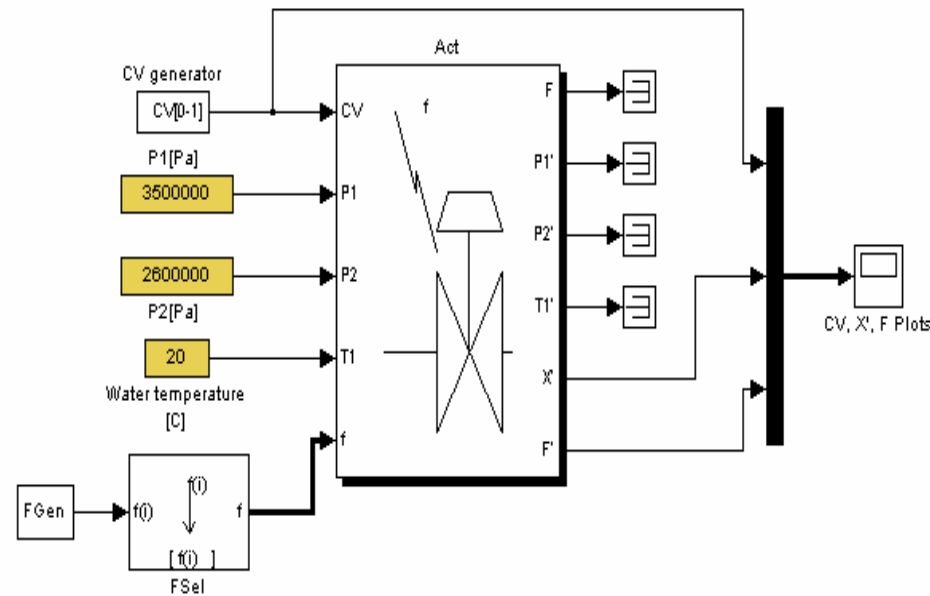


Detection Results for DO





Valve Model



Simulation Conditions

- Normal Condition
- F1: Valve Clogging
- F2: Valve Plug or Seat Sedimentation
- F3: Valve Plug or Seat Erosion

CV: Process Control Value

X: Valve Plug Displacement

F: Flow Rate

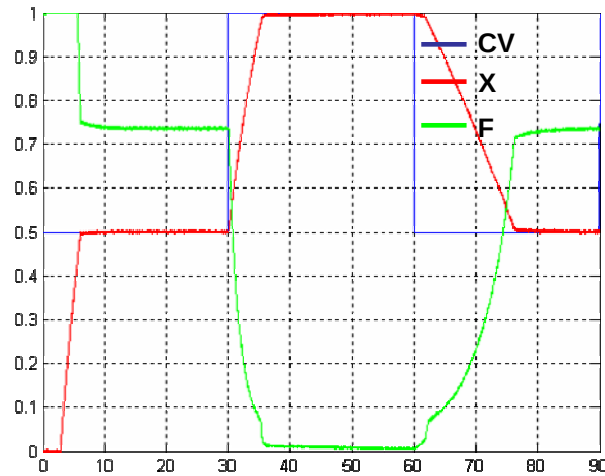
P1, P2: Pressures on Valve:
Inlet and Outlet

T1: Medium Temperature

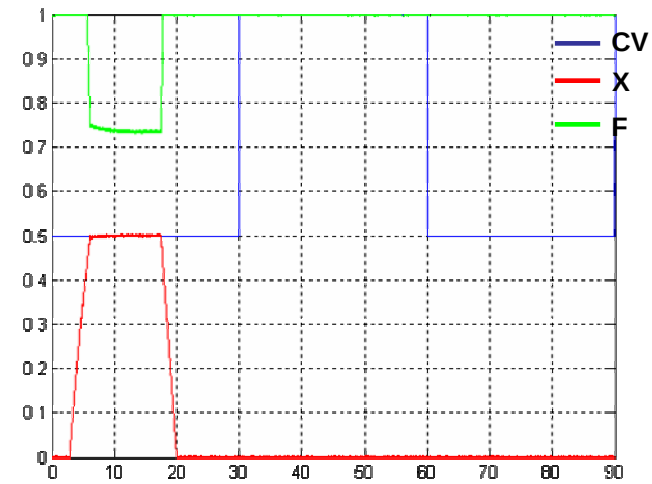




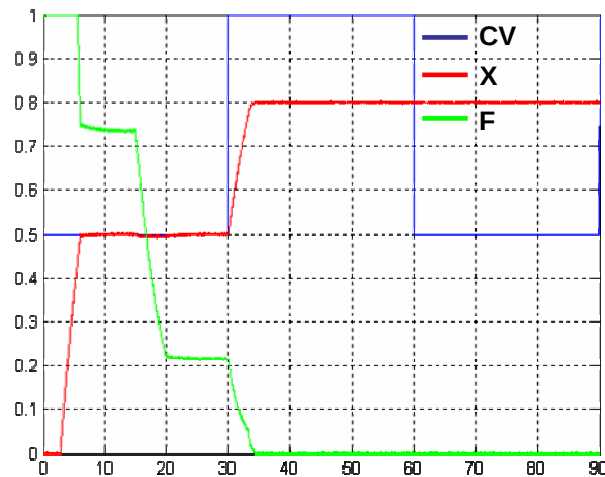
Valve Response



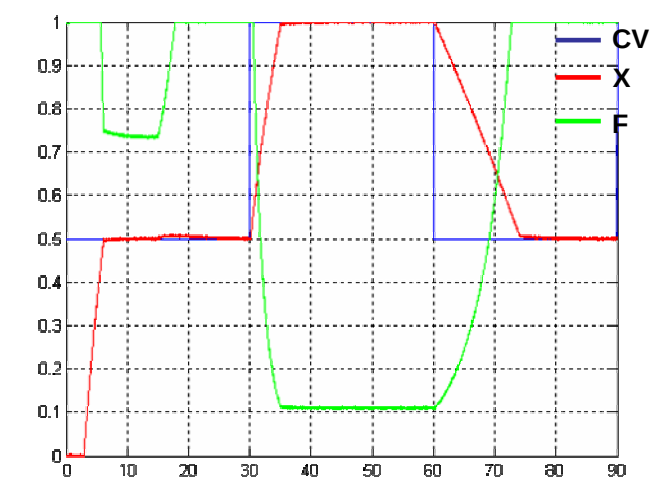
Normal Condition



F1 – Valve Clogging



F2 – Valve Plug or Seat Sedimentation



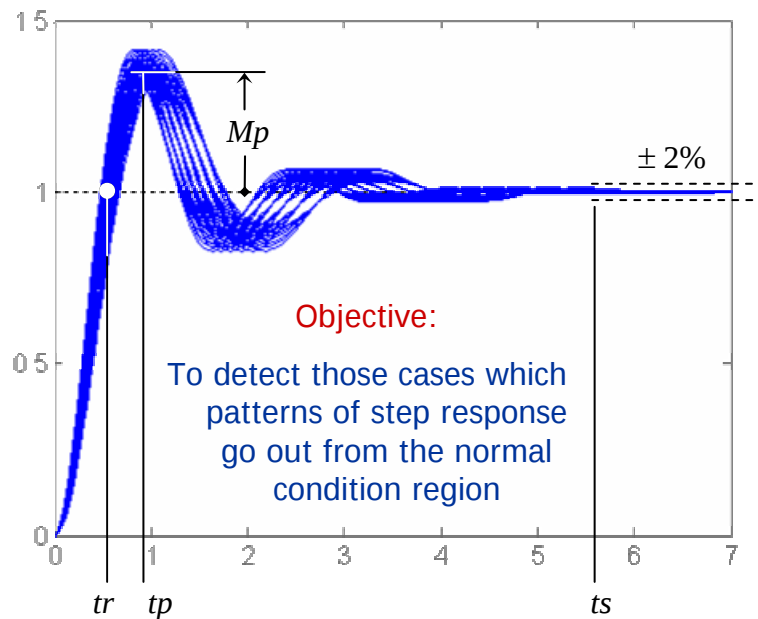
F3 – Valve Plug or Seat Erosion



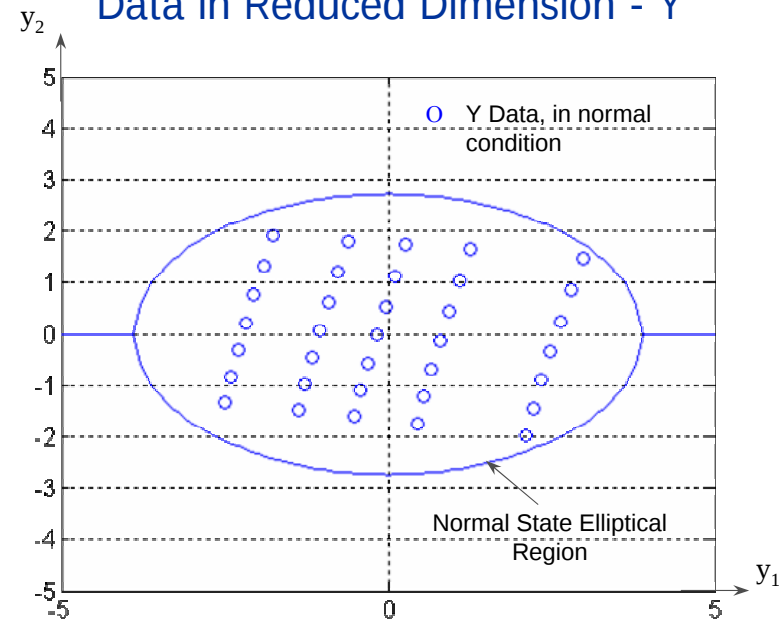
Case of Study: Second Order System

$$\frac{C(s)}{U(s)} = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}, \quad 0.27 \leq \zeta \leq 0.33 \quad \text{y} \quad 3 \leq \omega_n \leq 4$$

Normal Behavior of Step Response



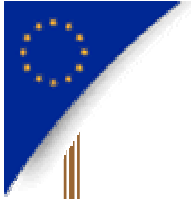
Data in Reduced Dimension - Y



$$X = [tr \quad tp \quad Mp \quad ts]_{(35 \times 4)}$$

$$Y_{(35 \times 2)} = \tilde{X} V_T$$



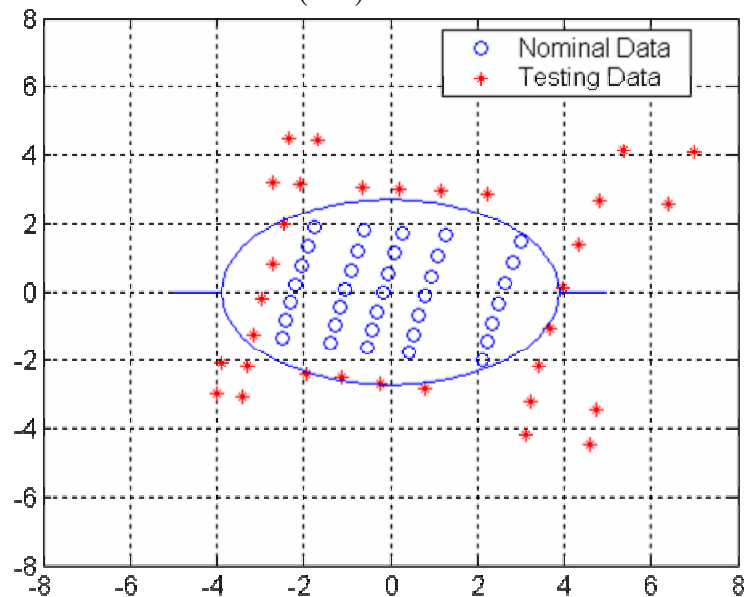


Normal and Fault Region

Testing Data:

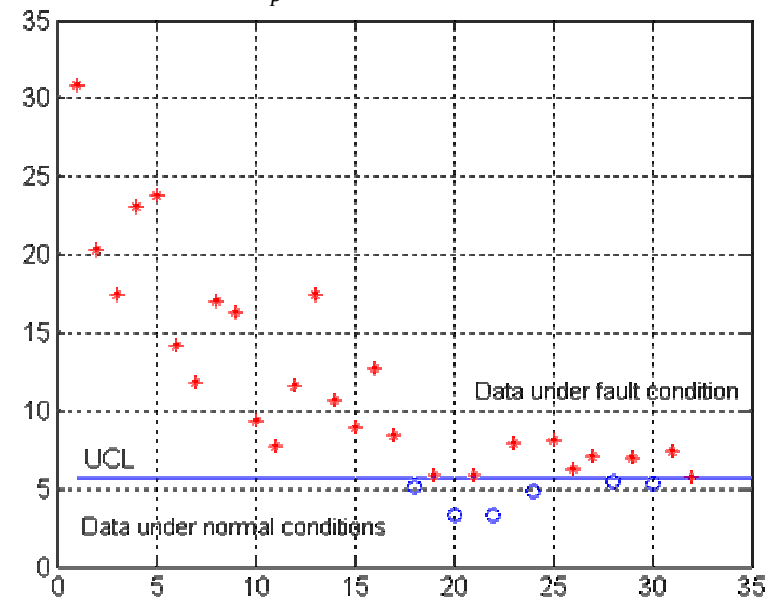
$$X_p = [tr_p \ tp_p \ Mp_p \ ts_p]_{(32 \times 4)}$$

$$y_{p(1 \times 2)} = \tilde{x}_p V_T$$



Nominal and testing data in the k-dimensional plane

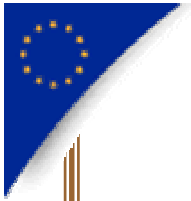
$$T_{y_p}^2 = y_p S_Y^{-1} y_p'$$



$T_{y_p}^2$ parameters and UCL limit

$$T_{y_p}^2 = f(tr_p, tp_p, Mp_p, ts_p, V_T, S_Y)$$



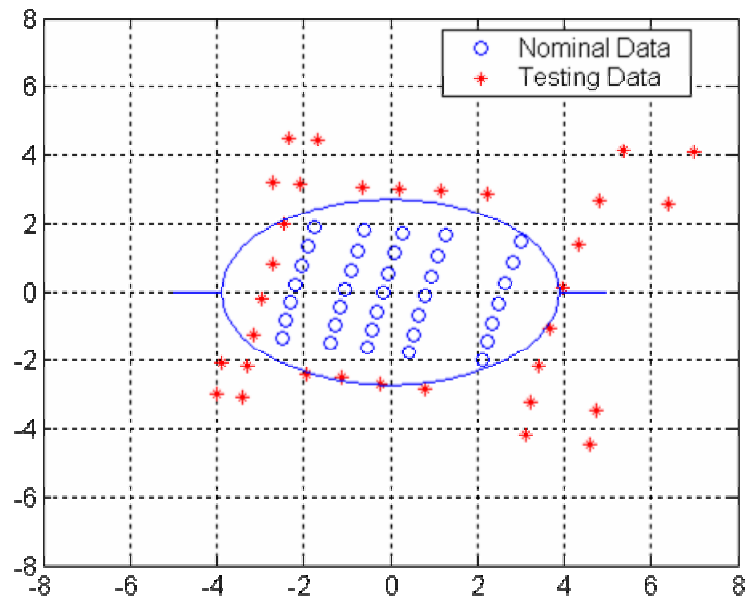


Results

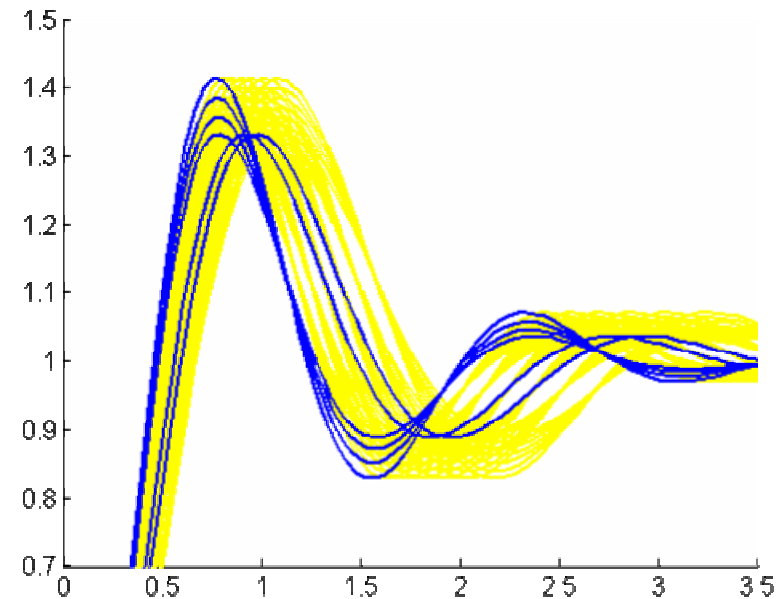
Testing Data:

$$X_p = [tr_p \ tp_p \ Mp_p \ ts_p]_{(32 \times 4)}$$

$$y_{p(1 \times 2)} = \tilde{x}_p V_T$$



Nominal and testing data in the k-dimensional plane



Step responses of the six cases which are inside the nominal region







Principal Components Analysis, PCA

- Given a set of observations: $X_{(n \times m)} = [X_1 \ X_2 \ \dots \ X_m]$, PCA expresses the m-variables in a reduced dimension through the transformation, $Y_{(n \times k)} = \tilde{X}V_T$; keeping the most of the variability (information) of the original data
- It is possible to make a selection of those variables which are more descriptive of the interest phenomena

From: $Y_{(j)} = v_{(j)1}\tilde{X}_1 + \dots + v_{(j)m}\tilde{X}_m \quad \text{para} \quad j = 1, 2, \dots, k$

The *Load Factors* are defined as: $L_{ji} = v_{ji}\sqrt{\lambda_j} \in [0,1] \quad \text{para} \quad i = 1, 2, \dots, m$

The most influential variables are those with the highest load factors

Objective:

Get a low dimension 'external model' as reference, from measured data, only considering deviations due to common causes

