

# Regulation under Wealth Constraints\*

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## Abstract

This article studies the problem of regulating a monopolist with unknown marginal cost. The problem described differs from Baron and Myerson [1982] because we suppose that the regulator faces a cash-in-advance constraint. The introduction of such a constraint may lead to the collapse of the incentive system.

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## 1 Introduction

The problem we concentrate on is the following: a public authority faces a monopolistic producer with unknown cost<sup>1</sup>. The authority tries to provide a public utility (bridge, road or sewer system) to a bunch of consumer. This public utility is produced by the monopolist and financed by government transfers. The contract offered by the government to the firm specifies the quantities that should be produced and a level of transfer. We assume that the government doesn't know the cost function of the firm.

The originality of this paper is to add up to the standard problem macroeconomics constraints. We will suppose that the public authority has only limited funds at disposal. This constraints limits the possibilities for the government to buy the full consumer surplus associated with the public utility. We believe that such constraints may be particularly relevant for the case of developing countries.

We show that the presence of a wealth constraint distorts -in a non linear way- the quantity produced by each type of firm. These 'third best' distortions that come on top of the traditional 'second best' distortions are necessary to fulfill the wealth constraint. But these distortions may lead to the collapse of the incentive system: it may be impossible to separate the different types of firms. And hence, when the government is constrained, bunching is a non trivial issue.

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<sup>1</sup>The framework is similar to Baron and Myerson [1982] except that the firm has no fixed cost.

## 2 Model

Our model is a simple model of adverse selection: the principal (public authority) contracts with an agent (monopolistic private firm) for the provision of a public utility. The agent is responsible of the production and the principal finances the production with transfers. At the time of contracting, the principal does not know the cost conditions under which the firm can produce. We will assume that the good is produced by the firm with a technology exhibiting constant return to scale. The cost function of the firm is  $\theta q$ , where  $\theta$  is a constant marginal cost and  $q$  is the quantity produced<sup>2</sup>. The marginal cost is private information to the firm. The principal only knows that  $\theta \in \Theta \equiv \{\theta_1, \theta_2\}$  with  $\theta_1 < \theta_2$  and the probabilities  $v_1$  and  $v_2 = 1 - v_1$  of agent being  $\theta_1$  and  $\theta_2$ . We call  $\Delta\theta = \theta_2 - \theta_1$ .

The utility of the agents is:

$$U^A = T - \theta q$$

Where  $T$  is the transfer paid by the principal to the agent. Firm accepts the contract if it gets more than its outside option normalized to zero.

When the agent produces a quantity  $q$ , the principal collects a surplus  $S(q)$ . We assume that  $S' \geq 0$ ,  $S'(0) = +\infty$ ,  $S'' < 0$  and  $S''' > 0$ . Our assumptions on  $S$  ensures that it is optimal to have all types producing.

The utility of the principal is:

$$U^P = S(q) - T$$

The regulator offers a contract specifying the transfer  $T$  and the quantity  $q$ . We call  $T_1, q_1$ , the transfer paid to the type  $\theta_1$  agent when he produces  $q_1$  and similarly,  $T_2, q_2$ , the transfer and production of  $\theta_2$  agent.

The cash in advance constraint limits the transfer: they cannot exceed an upper limit denoted  $\bar{T}$ .

## 3 Results

### 3.1 Second best equilibrium

Without cash in advance constraint, the objective of the principal is:

Program [P1]

$$\max_{q_1, q_2, T_1, T_2} v_1(S(q_1) - T_1) + v_2(S(q_2) - T_2)$$

s.t.  $\forall i, j = 1, 2$ :

$$T_1 - \theta_1 q_1 \geq T_2 - \theta_1 q_2 \quad (IC_1)$$

$$T_2 - \theta_2 q_2 \geq T_1 - \theta_2 q_1 \quad (IC_2)$$

$$T_1 - \theta_1 q_1 \geq 0 \quad (IR_1)$$

$$T_2 - \theta_2 q_2 \geq 0 \quad (IR_2)$$

The two relevant constraints of this problem are  $IC_1$  and  $IR_2$ .

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<sup>2</sup>Equivalently, we could interpret  $q$  as the quality of the good produced.

**Proposition 1** *The solution to the problem [P1] is given by:*

$$q_1^{SB} = S'^{-1}(\theta_1) \quad (1)$$

$$q_2^{SB} = S'^{-1}\left(\theta_2 + \frac{v_1}{v_2}\Delta\theta\right) \quad (2)$$

$$T_1 = \theta_1 q_1^{SB} + \Delta\theta q_2^{SB}$$

$$T_2 = \theta_2 q_2^{SB}$$

This solution is standard.

### 3.2 Wealth constrained equilibria

We now introduce the wealth constraint. The constraint implies that the principal cannot transfer the agent more than  $\bar{T}$ . We said that the constraint is *relevant* if the maximal transfer  $\bar{T}$  is smaller than the highest transfer paid by the principal in the second best equilibrium<sup>3</sup>. The principal's optimization program becomes:

Program [P2]:

$$\max_{q_1, q_2, T_1, T_2} v_1(S(q_1) - T_1) + v_2(S(q_2) - T_2)$$

s.t.  $(IC_1)$ ,  $(IC_2)$ ,  $(IR_1)$ ,  $(IR_2)$  and

$$T_1, T_2 \leq \bar{T} \quad (WC)$$

**Lemma 1** *When  $\bar{T} \leq \theta_1 q_1^{SB} + \Delta\theta q_2^{SB}$ , the efficient type agent  $(\theta_1)$  will be paid  $\bar{T}$ .*

**Proof.** If  $\bar{T} < T_1^{SB}$ , the solution of P1 cannot be replicated in P2. Then, at least one of the transfers in P2 is given by the constraint (WC). A necessary condition for implementation is:  $q_1 \geq q_2$  and  $T_1 \geq T_2$ . Then the constraint (WC) binds (at least) for  $T_1$ . ■

Using the relevant constraints  $IC_1$ ,  $IR_2$  and the result of lemma 1, the program [P2] can be rewritten as:

Program[P3]:

$$\max_{q_1, q_2} v_1(S(q_1) - \bar{T}) + v_2(S(q_2) - \theta_2 a_2)$$

s.t.

$$(\mu_1) \quad \bar{T} = \theta_1 q_1 + \Delta\theta q_2$$

$$(\mu_2) \quad T_2 = q_2 \theta_2 \leq \bar{T}$$

The solution of this optimization program is given in our second proposition.

**Proposition 2** *(i) If  $\theta_1 \geq v_1 \theta_2$  and  $\bar{T} \leq \bar{T}^* = \theta_2 S'^{-1}\left(\frac{\theta_2 \theta_1 v_2}{\theta_1 - v_1 \theta_2}\right)$ , the equilibrium is a pooling equilibrium:*

$$q_1 = q_2 = \frac{\bar{T}}{\theta_2} \quad (3)$$

$$T_1 = T_2 = \bar{T} \quad (4)$$

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<sup>3</sup>The constraint is relevant if:  $\bar{T} \leq \theta_1 q_1^{SB} + \Delta\theta q_2^{SB}$ .

(ii) otherwise, the equilibrium is a separating equilibrium characterized by the following first order conditions:

$$q_1^{WC} = S'^{-1}\left(\frac{\mu_1}{v_1}\theta_1\right) \quad (5)$$

$$q_2^{WC} = S'^{-1}\left(\theta_2 + \frac{\mu_1}{v_2}\Delta\theta\right) \quad (6)$$

$$\bar{T} - \theta_1 q_1^{WC} - \Delta\theta q_2^{WC} = 0 \quad (7)$$

And the transfers are give by the constraints WC and IR<sub>2</sub>.

$$T_1 = \bar{T} \quad (8)$$

$$T_2 = \theta_2 q_2^{WC} \quad (9)$$

The proof of proposition 2 is relegated to an appendix. Before explaining the result of proposition 2, it is useful to make some comparative static and study the effect of a change in  $\bar{T}$ . This is done in proposition 3:

**Proposition 3** *In the separating equilibrium, the value of  $\mu_1$  is a decreasing an convex function of  $\bar{T}$ , with  $\lim_{\bar{T} \rightarrow 0} \mu_1 = +\infty$  and  $\lim_{\bar{T} \rightarrow T_1^{SB}} \mu_1 = v_1$*

**Proof.** (i) From the first order conditions we have:  $\bar{T} = \theta_1 S'^{-1}\left(\frac{\mu_1}{v_1}\theta_1\right) + \Delta\theta S'^{-1}\left(\theta_2 + \frac{\mu_1}{v_2}\Delta\theta\right)$ . Call the right hand side  $G(\mu_1)$ . Then  $\mu_1 = G^{-1}(\bar{T})$ . Given our assumptions on  $S$ ,  $G$  is increasing and concave, because  $S'^{-1}$  is increasing and concave. Then  $G^{-1}$  is decreasing and convex. (ii) At the limit when  $\bar{T}$  goes to  $T_1^{SB}$ , the problem is identical to the problem  $P1$  and therefore the solution is identical. i.e.  $\mu_1 = v_1$ . When  $\bar{T}$  goes to zero, the right hand side of the (7) must go to zero. Given that  $S'(0) = +\infty$ , we have that  $G^{-1}(0) = +\infty$ . ■

Now we turn back to the equilibria described in proposition 2. On the top of the traditional second best trade off between efficiency and rent extraction that leads to distortions in  $q_2$ , there is now a third best distortion necessary to fulfill the wealth constraint. If we call  $\mu'_1 = \mu_1 - v_1$ , we can rewrite (5) and (6) in order to isolates the second and third best distortions:

$$S'(q_1) = \theta_1 + \frac{\mu'_1}{v_1}\theta_1 \quad (10)$$

$$S'(q_2) = \theta_2 + \frac{v_1}{v_2}\Delta\theta + \frac{\mu'_1}{v_2}\Delta\theta \quad (11)$$

If we compare these expressions with the second best equilibrium, it is clear that the last terms on the right hand member measures the distortions imposed to fulfill the wealth constraint. As established by proposition 3, these third best distortions increases when the constraint becomes more severe ( $\mu'_1$  increases).

The addition of a third best distortion in  $q_1$  and  $q_2$  may lead to the collapse of the incentive system. It will be the case if the distorted actions doesn't satisfy the necessary condition for implementation, namely keeping  $q_1$  greater than  $q_2$ <sup>4</sup>. If  $q_1$  is more distorted than  $q_2$ , there is a level of  $\mu'_1$  and a corresponding level of  $\bar{T}$  (called  $\bar{T}^*$ ) such that the value of  $q_1$  given by (5) is smaller than the value of  $q_2$  given by (6). Therefore, for these values of the  $\bar{T}$ , the only feasible mechanism is a pooling mechanism.

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<sup>4</sup>This question is not an issue in the second best problem, because only the action of the inefficient agent ( $\theta_2$ ) is distorted. When both actions are modified, the question of keeping the action scheme decreasing becomes crucial.

## 4 Conclusion

In this paper, we have shown that when the government is constrained on the level of transfer he can make to the firms, there is under-provision of public facilities. Moreover pooling contracts where both types of firm produce the same quantities and receive the same transfer may be the optimal contract. In the classical adverse selection problem, and given that the model satisfies some regularity conditions, pooling contracts are ruled out. In our model, pooling contracts may be optimal as soon as the difference between the highest marginal cost and the lowest one is not too big. So pooling is an issue when the regulator faces cash-in-advance constraints. Wealth constraints may lead to low-powered incentive scheme where the regulator pays a constant fee for a fixed quantity.

## A Proof of proposition 2

The first order conditions of  $P3$  are:

$$S'(q_1) = \frac{\mu_1}{v_1}\theta_1 \quad (12)$$

$$S'(q_2) = \theta_2 + \frac{\mu_1}{v_2}\Delta\theta + \frac{\mu_2}{v_2}\theta_2 \quad (13)$$

$$\bar{T} - \theta_1 q_1 - \Delta\theta q_2 = 0 \quad (14)$$

$$\mu_2(\bar{T} - \theta_2 q_2) = 0 \quad (15)$$

We know by lemma 1 that  $\mu_1 > 0$  if the wealth constraint is relevant. There are two possible solutions to this system of equation: a separating solution when  $\mu_2 = 0$  and a pooling solution when  $\mu_2$  is positive.

If  $\mu_2 > 0$ , (15) becomes  $\bar{T} = \theta_2 q_2$ , then  $q_2 = \frac{\bar{T}}{\theta_2}$ . Replacing this value in (14), we have  $q_1 = q_2 = \frac{\bar{T}}{\theta_2}$ .

If  $\mu_2 = 0$ , the separating solution is given by:

$$S'(q_1) = \frac{\mu_1}{v_1}\theta_1 \quad (16)$$

$$S'(q_2) = \theta_2 + \frac{\mu_1}{v_2}\Delta\theta \quad (17)$$

$$\bar{T} - \theta_1 q_1 - \Delta\theta q_2 = 0 \quad (18)$$

To know which solution applies, we check when  $\mu_2$  is positive. As long as  $q_2$  is smaller than  $q_1$ , the transfer  $T_2$  is smaller than  $\bar{T}$ . Therefore, the second wealth constraint is slack when  $q_2 \leq q_1$ . This corresponds to the following condition:

$$\frac{\mu_1}{v_1}\theta_1 \geq \theta_2 + \frac{\mu_1}{v_2} \quad (19)$$

where the value of  $\mu_1$  is given by (18). Take the limit case where (19) is satisfied with equality, and solve for  $\mu_1$  we have:  $\mu_1 = \frac{v_2\theta_2\theta_1}{\theta_1 - v_1\theta_2}$ . As long as the actual  $\mu_1$  is smaller than this value (call it  $\mu_1^*$ ),  $q_2$  is smaller than  $q_1$ .

$\mu_1^*$  is negative if  $\theta_1 \leq v_1\theta_2$ . In this case, whatever  $\bar{T}$ ,  $q_2$  is smaller than  $q_1$ , except in the limit case where  $\bar{T}$  is null where both quantities are set equal to zero.

If  $\theta_1 > v_1\theta_2$ , we have to find the value of  $\bar{T}$  that generates value of  $\mu_1$  equals to  $\mu_1^*$ . To do this, we solve (16), (17) and (18) for  $\bar{T}$  when  $\mu = \mu_1^*$ . This gives a value  $\bar{T}^* = \theta_2 S'^{-1}(\frac{\theta_2 \theta_1 v_2}{\theta_1 - v_1 \theta_2})$ . We anticipate the results of proposition 3 that shows that  $\mu_1$  increases when  $\bar{T}$  decreases. Hence, when  $\bar{T} \leq \bar{T}^*$  and  $\theta_1 > v_1\theta_2$ ,  $\mu_2$  is positive and the solution is the pooling equilibrium. When  $\bar{T} \geq \bar{T}^*$ ,  $\mu_2$  is null and the solution is the separating equilibrium.

The second order conditions of P3 are always satisfied thanks to the concavity of the problem.

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