Workpackage 3

# Workpackage 3

IUAP Study Day

### Teams

- UCL/INMA
- KUL/KUL1
- KUL/KUL2
- ULg/SYST
- UG/SYSTeMS
- Themes
  - Optimization
  - Stability and Model Reduction
  - Linear algebra, Multiresolution and Simulation

Structured matrices depend on O(n) data rather than  $O(n^2)$  data (like a dense matrix). Examples are

- Sparse matrices
- Patterned matrices (Hankel, Toeplitz, FFT, Wavelet)
- Hierarchical matrices
- Rank structured matrices

Matrix problem complexity is then  $\mathcal{O}(n^2)$  rather than  $\mathcal{O}(n^3)$ .



Empty submatrices are low rank and colored ones are full rank

Continued collaborations and joint publications between

- KUL1
- KUL2
- UCL

Developed techniques are useful for other workpackages

- WP1 : Identification
- ▶ WP5 : Biomedical data analysis
- WP3 : Simulation, graph analysis, structured optimization, multiresolution analysis

Computing the roots of a monic polynomial p(z) = p₀ + p₁z + p₂z² + ... + p<sub>n−1</sub>z<sup>n−1</sup> + z<sup>n</sup> amounts to computing the eigenvalues of a 'companion' matrix H:

$$H = \begin{bmatrix} 0 & -p_0 \\ 1 & \ddots & -p_1 \\ \ddots & \vdots \\ & 1 & -p_{n-1} \end{bmatrix}.$$

► LAPACK solves this problem by the *QR*-algorithm but destroys the structure and requires *O*(*n*<sup>3</sup>) flops

Rewriting the companion matrix as H = U + R:

$$H = \begin{bmatrix} 0 & 1 \\ 1 & \ddots & \\ & \ddots & \\ & & 1 & 0 \end{bmatrix} + \begin{bmatrix} 0 & -p_0 - 1 \\ 0 & \ddots & -p_1 \\ & \ddots & 0 & \vdots \\ & & 0 & -p_{n-1} \end{bmatrix}$$

where H is Hessenberg, U is unitary and R is rank one, allows to preserve this structure along the QR algorithm iterations.

This results in an  $\mathcal{O}(n^2)$  algorithm which was succesfully applied to polynomials of degree up to a few thousands.

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### Low-rank approximations: joint publications

Low Rank Approximation



 $S_+(p, n)$  is the set of all symmetric positive-semidefinite  $n \times n$  matrices of rank *p*:

```
S_+(\rho, n) = \{YY^T : Y \in \mathbf{R}^{n \times \rho}, \operatorname{rk}(Y) = \rho\}.
```

 $S_+(p, n)$  leads to

- various geometries: quotient or embedded;
- various computational problems: geodesics, means, statistics...;
- various applications:
  - covariance matrices (e.g., in finance)
  - semidefinite programming (e.g., for maximal cut and sparse PCA)
  - kernels (e.g., in machine learning)
  - diffusion tensors (e.g., in medical imaging).



 $\mathcal{A}$  Rank- $(R_1, R_2, R_3)$  approx.

Rank-R approx.

Applications of the best rank-(R1, R2, R3) approximation:

- Dimensionality reduction for independent component analysis (ICA)
- Dimensionality reduction for CANDECOMP
- Image analysis and recognition
- Multi-way data analysis