

Random Matrices

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Part 7) Biorthogonal Ensembles

- **Vandermonde determinant**

$$\Delta(\lambda) = \prod_{j < k} (\lambda_j - \lambda_k)^2$$

- **Eigenvalue density of invariant ensemble**

$$\frac{1}{Z_n} \Delta(\lambda)^2 \prod_{j=1}^n e^{-V(\lambda_j)} = \frac{1}{Z_n} \left(\det [f_j(\lambda_k)]_{j,k=1,\dots,n} \right)^2$$

with

$$f_j(x) = x^{j-1} e^{-\frac{1}{2} V(x)}$$

- This is an **OP ensemble**

Biorthogonal ensemble

- Joint probability density function on $\mathbb{R}^n$ of the form

$$\frac{1}{Z_n} \det [f_j(x_k)]_{j,k} \det [g_j(x_k)]_{j,k}$$

is a **biorthogonal ensemble**

- It is always **determinantal** Borodin (1998)
- Correlation kernel is

$$K_n(x, y) = \sum_{j=1}^n \sum_{k=1}^n f_j(x) [A^{-1}]_{k,j} g_k(y)$$

where A^{-1} is the inverse of the matrix

$$A = (A_{j,k}), \quad A_{j,k} = \int f_j(x) g_k(x) dx$$

Biorthogonal functions

- Change basis functions

$$\begin{aligned}f_1, \dots, f_n &\mapsto \phi_1, \dots, \phi_n \\g_1, \dots, g_n &\mapsto \psi_1, \dots, \psi_n\end{aligned}$$

- New basis is **biorthogonal** if

$$\int_{-\infty}^{\infty} \phi_j(x) \psi_k(x) dx = \delta_{j,k}$$

- Then correlation kernel is single sum

$$K_n(x, y) = \sum_{j=1}^n \phi_j(x) \psi_j(y)$$

Non-intersecting paths

Example: Assume $X_1(t), \dots, X_n(t)$ are independent copies of **one-dimensional diffusion process** conditioned such that

- $X_j(0) = a_j$ with $a_1 < a_2 < \dots < a_n$
- $X_j(T) = b_j$ with $b_1 < b_2 < \dots < b_n$,
- the paths do not intersect

Then positions of the paths at any time $t \in (0, T)$ are **biorthogonal ensemble Karlin-McGregor (1959)**

Biorthogonal ensemble

- Let $p_t(x, y)$ be the **transition probability** density
For Brownian motion

$$p_t(x, y) = \frac{1}{\sqrt{2\pi t}} e^{-\frac{(x-y)^2}{2t}}$$

- **Biorthogonal ensemble** at time t with functions

$$f_j(x) = p_t(a_j, x), \quad g_j(x) = p_{T-t}(x, b_j)$$

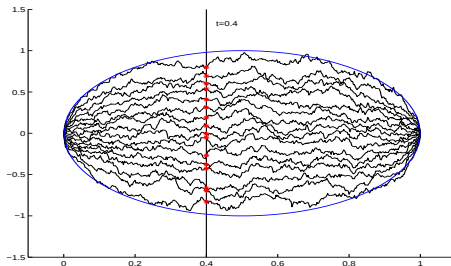
- This is not an OP ensemble

Confluent limit

- Take Brownian motion, and confluent limit

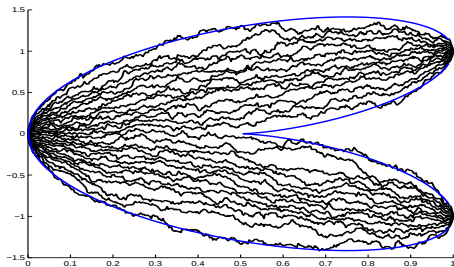
$$a_j \rightarrow 0, \quad b_j \rightarrow 0$$

- Positions at time t are eigenvalues of GUE (up to scaling)



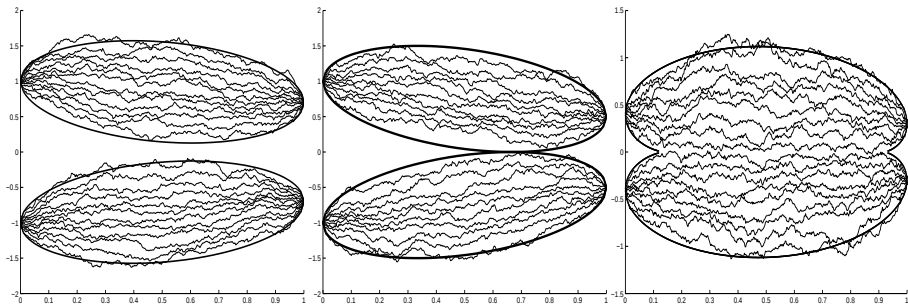
Cusp point

- All $a_j \rightarrow 0$, half of $b_j \rightarrow 1$, other half of $b_j \rightarrow -1$



Tacnode problem

- Two starting points, two ending points



Part 8) Multiple Orthogonal Ensembles

- **Biorthogonal ensemble of the form**

$$\frac{1}{Z_n} \Delta(x) \det [f_j(x_k)]$$

with $\Delta(x)$ the **Vandermonde determinant**

- **Suppose**

f_j s are: $x^{j-1} w_k(x)$ for $j = 1, \dots, n_k$, $k = 1, \dots, r$

with small number r .

- **Biorthogonal functions take the form**

$$\phi_j(x) = P_{j-1}(x), \quad \psi_j(x) = \sum_{k=1}^r A_{j,k}(x) w_k(x)$$

with **polynomials**

$$\deg P_{j-1} = j - 1, \quad \sum_{k=1}^r \deg A_{j,k} = j - 1.$$

Type II multiple orthogonality

- P_n satisfies

$$\int_{-\infty}^{\infty} P_n(x) x^{j-1} w_k(x) dx = 0, \quad j = 1, \dots, n_k, \quad k = 1, \dots, r.$$

- This is **multiple orthogonality** of type II
- Multi-index notation $P_n = P_{n_1, \dots, n_r}$
- Polynomials $A_{n,k}$ are **type I MOPs**

Examples of MOP ensembles

- Non-intersecting Brownian motions, with one starting point and r ending points
- Eigenvalues of **external source model**

$$\frac{1}{Z_n} e^{-\text{Tr}(V(M) - AM)} dM$$

with deterministic A having r distinct eigenvalues

- Eigenvalues of matrix M_1 in **two matrix model**

$$\frac{1}{Z_n} e^{-\text{Tr}(V(M_1) + W(M_2) - \tau M_1 M_2)} dM_1 dM_2$$

if W has degree $r + 1$

More examples

- Non-intersecting **squared Bessel paths**
- Eigenvalues in **normal matrix model** (complex matrices)

$$\frac{1}{Z_n} e^{-\text{Tr}(M^* M - V(M) - V(M^*))} dM$$

if V has degree $r + 1$

- **Squared singular values** of product

$$X_r \dots X_2 X_1$$

of independent Ginibre random matrices

Useful tools for asymptotic analysis

- Riemann-Hilbert problem **YES**
- Equilibrium problem **SOMETIMES**

Part 9) RH problem for MOPs

Riemann-Hilbert problem (case $r = 2$)

RH problem of size 3×3 (if $r = 2$)

RH-Y1 $Y : \mathbb{C} \setminus \mathbb{R} \rightarrow \mathbb{C}^{3 \times 3}$ **is analytic.**

RH-Y2 Y **has boundary values for $x \in \mathbb{R}$, denoted by $Y_{\pm}(x)$, and**

$$Y_+(x) = Y_-(x) \begin{pmatrix} 1 & w_1(x) & w_2(x) \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{for } x \in \mathbb{R}.$$

RH-Y3 **As $z \rightarrow \infty$,**

$$Y(z) = \left(I + O\left(\frac{1}{z}\right) \right) \begin{pmatrix} z^{n_1+n_2} & 0 & 0 \\ 0 & z^{-n_1} & 0 \\ 0 & 0 & z^{-n_2} \end{pmatrix}$$

Solution in terms of type II MOPs

Theorem (Van Assche, Geronimo, K (2001))

RH problem has a **unique solution** if and only if the type II MOP P_{n_1, n_2} uniquely exists.

In that case the first row of Y is given by

$$\begin{pmatrix} P_{n_1, n_2}(z) & \frac{1}{2\pi i} \int_{-\infty}^{\infty} \frac{P_{n_1, n_2}(s) w_1(s)}{s - z} ds & \frac{1}{2\pi i} \int_{-\infty}^{\infty} \frac{P_{n_1, n_2}(s) w_2(s)}{s - z} ds \\ * & * & * \\ * & * & * \end{pmatrix}$$

- Other rows contain P_{n_1-1, n_2} and P_{n_1, n_2-1}

- The type I MOPs are in the **inverse** of Y

$$Y^{-1}(z) = \begin{pmatrix} -\int_{-\infty}^{\infty} \frac{\psi(s)}{s-z} ds & * & * \\ 2\pi i A_1(z) & * & * \\ 2\pi i A_2(z) & * & * \end{pmatrix}$$

where $\psi(s) = A_1(s)w_1(s) + A_2(s)w_2(s)$

Christoffel Darboux formula

Theorem (Bleher-K (2004) for $r = 2$)

The correlation kernel K_n for the MOP ensemble is given by

$$K_n(x, y) = \frac{1}{2\pi i(x - y)} \begin{pmatrix} 0 & w_1(y) & w_2(y) \end{pmatrix} Y_+^{-1}(y) Y_+(x) \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

Extension to $r \geq 3$: [Daems-K \(2004\)](#)

Part 10) Equilibrium problem for MOPs (incomplete)

Vector equilibrium problem

- For a RH problem of size $(r + 1) \times (r + 1)$ we would need **r measures** $\mu_1, \dots, \mu_r$ and associated g -functions

$$g_j(z) = \int \log(z - s) d\mu_j(s)$$

- **Equilibrium problem** for vector of measures

General form of VEP

Minimize

$$\sum_{j=1}^r \sum_{k=1}^r c_{j,k} \iint \log \frac{1}{|x-y|} d\mu_j(x) d\mu_k(y) + \sum_{j=1}^r \int V_j(x) d\mu_j(x)$$

among **vector of measures** $(\mu_1, \dots, \mu_r)$ where

μ_j is supported on Σ_j with $\mu_j(\Sigma_j) = p_j$

and maybe extra conditions

- General existence and uniqueness result in case the interaction matrix $(c_{j,k})_{j,k=1,\dots,r}$ is **positive definite**

Hardy-K (2012)