

When are there enough model isomorphisms? Representing groupoids for classifying toposes

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On topological groupoids that represent theories, arXiv:2306.16331

Main result and overview

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Overview

- I. Recall the definition of the *topos of sheaves on a groupoid* and the *classifying topos* of a theory.
- II. Review an *example representing groupoid*.
- III. Define *elimination of parameters*.
- IV. Technically *restate the main theorem*, and give some applications.

Topological groupoids

Definition

A (small) groupoid $\mathbb{X} = (X_1 \rightrightarrows X_0)$ consists of a diagram of sets

$$\begin{array}{ccccc}
 X_1 \times_{X_0} X_1 & \xrightarrow{m} & X_1 & \begin{array}{c} \xrightarrow{t} \\ \xleftarrow{e} \\ \xrightarrow{s} \end{array} & X_0, \\
 & & \begin{array}{c} \curvearrowright \\ i \end{array} & &
 \end{array}$$

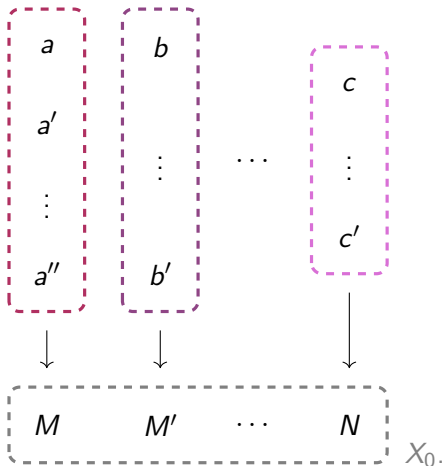
satisfying the ‘obvious’ equations.

A *topological groupoid* consists of topologies on X_0 and X_1 such that the above maps are continuous.

We say that \mathbb{X} is *open* if s (equivalently, t) is open.

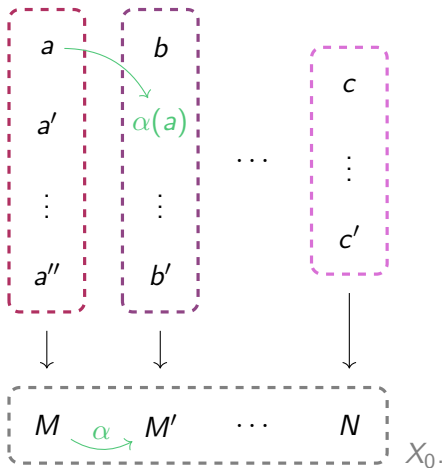
Equivariant sheaves on a groupoid

Given a groupoid \mathbb{X} , a discrete *bundle* on \mathbb{X} consists of a map $q: Y \rightarrow X_0$,



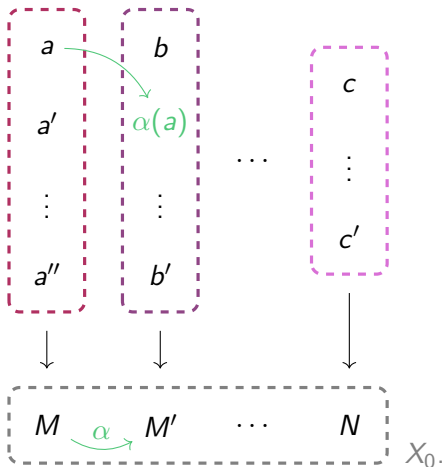
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Given a groupoid \mathbb{X} , a discrete *bundle* on \mathbb{X} consists of a map $q: Y \rightarrow X_0$, equipped with an X_1 -action $\beta: Y \times_{X_0} X_1 \rightarrow Y$,



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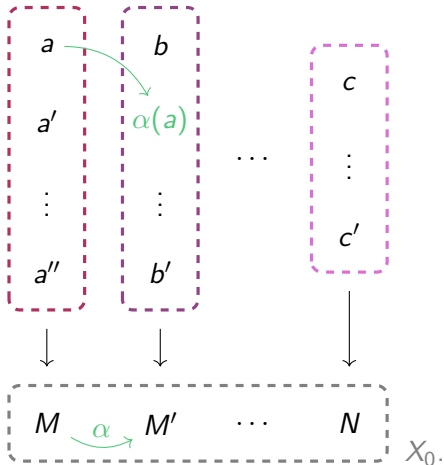


If \mathbb{X} is endowed with topologies, we say that a bundle is a *sheaf* if

- (i) $q: Y \rightarrow X_0$ is a local homeomorphism,
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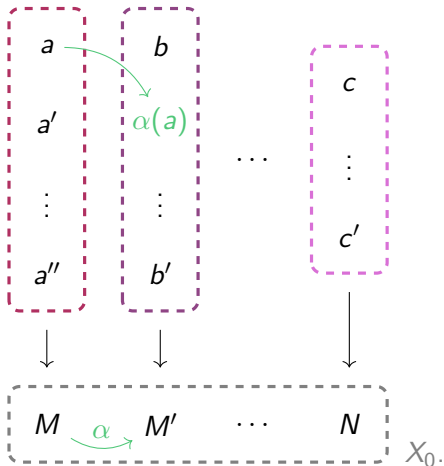
- (i) $q: Y \rightarrow X_0$ is a local homeomorphism,
- (ii) and $\beta: Y \times_{X_0} X_1 \rightarrow Y$ is continuous.

A *morphism* of sheaves is a continuous map $f: Y \rightarrow Y'$ such that the following commute:

$$\begin{array}{ccc}
 Y \times_{X_0} X_1 & \xrightarrow{f \times_{X_0} \text{id}_{X_1}} & Y' \times_{X_0} X_1 \\
 \beta \downarrow & & \downarrow \beta' \\
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Definition – topos of equivariant sheaves

The category of sheaves and their morphisms define a topos $\mathbf{Sh}(X)$.

Classifying topos

If a topos is 'like' a generalised space, then a *classifying topos* is 'like' a space whose points are models.

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Definition

If \mathbb{X} is a (open) topological groupoid for which

$$\mathbf{Sh}(\mathbb{X}) \simeq \mathcal{E}_{\mathbb{T}},$$

we say that \mathbb{X} *represents* \mathbb{T} .

Indexed structures

Let \mathbb{T} be a theory over a signature Σ whose set-based models are conservative.

We would expect the groupoid of *all* models to represent \mathbb{T} .

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Definition

Let M be a structure over a signature Σ .

Given a set \mathfrak{K} of *parameters*, a \mathfrak{K} -*indexing* of M consists of:

- (i) a subset $\mathfrak{K}' \subseteq \mathfrak{K}$,
- (ii) and an *expansion* of M to the signature $\Sigma \cup \{c_m \mid m \in \mathfrak{K}'\}$ such that M satisfies

$$\mathbb{T} \vdash_x \bigvee_{m \in \mathfrak{K}'} x = c_m,$$

i.e. every $n \in M$ is the interpretation of some parameter $m \in \mathfrak{K}'$.

Equivalently, this is a choice of partial surjection $\mathfrak{K}' \twoheadrightarrow M$.

The groupoid of all indexed models

Definition

Let $\mathbf{Ind}(\mathfrak{K})$ denote the groupoid:

- (i) whose objects are \mathfrak{K} -indexed models of \mathbb{T} ,
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Theorem (Awodey–Forssell [1], [4])

Let \mathfrak{K} be infinite. For suitable topologies on $\mathbf{Ind}(\mathfrak{K})$, there is an equivalence

$$\mathbf{Sh}(\mathbf{Ind}(\mathfrak{K})) \simeq \mathcal{E}_{\mathbb{T}}$$

if and only if the \mathfrak{K} -indexed models are *conservative* –

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This is just one example among many representing groupoids for \mathbb{T} .

In the following sections, we develop our characterisation.

Definable subsets of a single model

Let M be a model of \mathbb{T} with an indexing $\mathcal{K} \rightarrow M$.

(i) A *definable subset* is a subset of the form

$$\llbracket \vec{x} : \varphi \rrbracket_M = \{ \vec{n} \subseteq M \mid M \models \varphi(\vec{n}) \} \subseteq M^n$$

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(ii) A *definable subset with parameters* is a subset of the form

$$\llbracket \vec{x}, \vec{m} : \psi \rrbracket_M = \{ \vec{n} \subseteq M \mid M \models \psi(\vec{n}, \vec{m}) \} \subseteq M^n$$

for some formula $\{ \vec{x}, \vec{y} : \psi \}$ and a tuple of parameters $\vec{m} \subseteq \mathfrak{K}$.

Definables for a groupoid of models

For a groupoid \mathbb{X} of \mathbb{T} -models, a \mathfrak{K} -indexing of \mathbb{X} is a choice of \mathfrak{K} -indexing $\mathfrak{K} \rightarrow M$ for each $M \in \mathbb{X}$.

(i) A *definable* or *definable without parameters* is a subset of the form

$$\llbracket \vec{x} : \varphi \rrbracket_{\mathbb{X}} = \{ \langle \vec{n}, M \rangle \mid \vec{n} \subseteq M \in X_0, M \models \varphi(\vec{n}) \} \subseteq \coprod_{M \in X_0} M^n$$

for some formula $\{ \vec{x} : \varphi \}$.

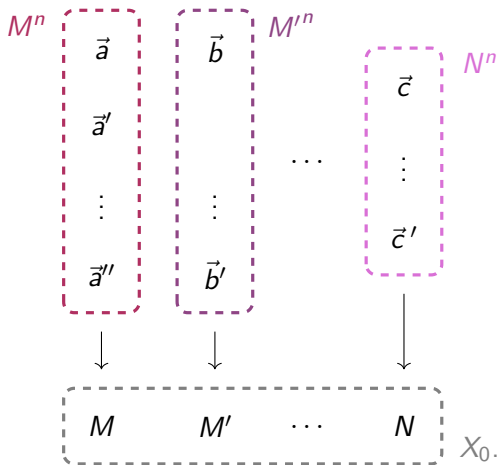
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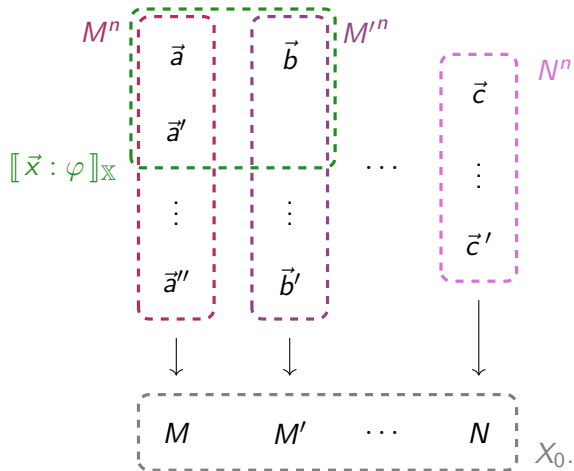
Interpreting definables and elimination of parameters

For each n , there is a bundle



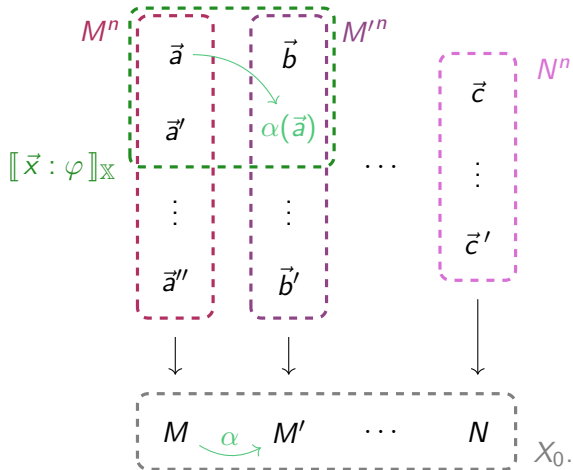
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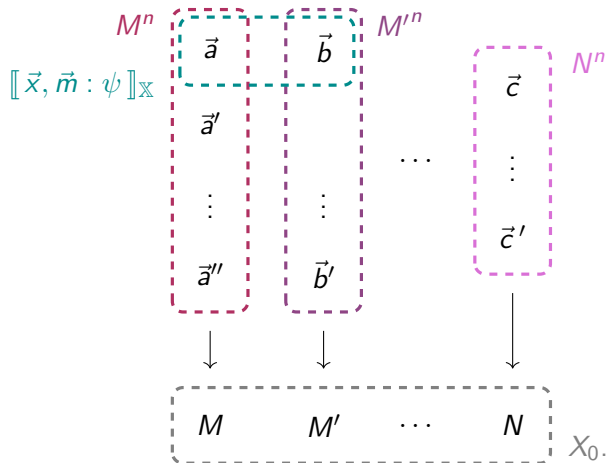
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Note that $\llbracket \vec{x} : \varphi \rrbracket_{\mathbb{X}}$ is *stable* under the X_1 -action.

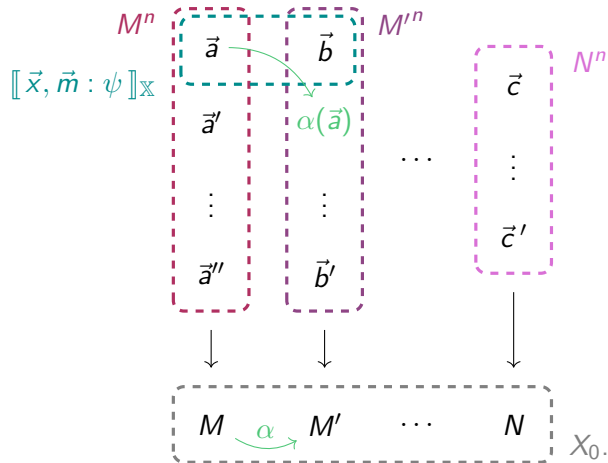
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Each definable with parameters also defines a subset



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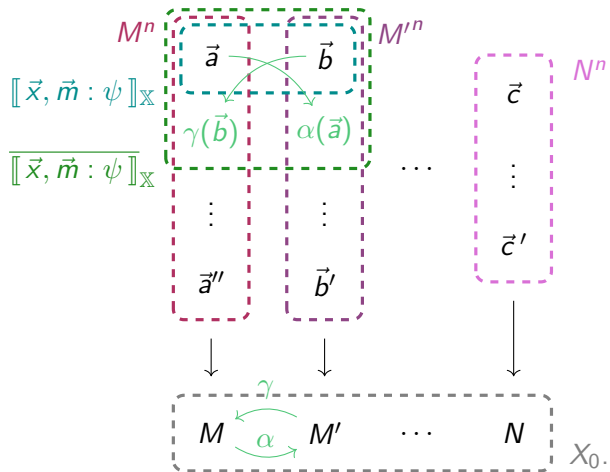
Each definable with parameters also defines a subset



However, $[[\vec{x}, \vec{m} : \psi]]_{\mathbb{X}}$ is not stable under the X_1 -action.

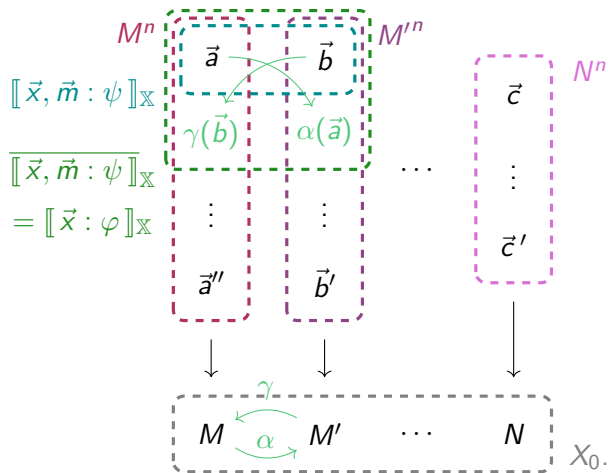
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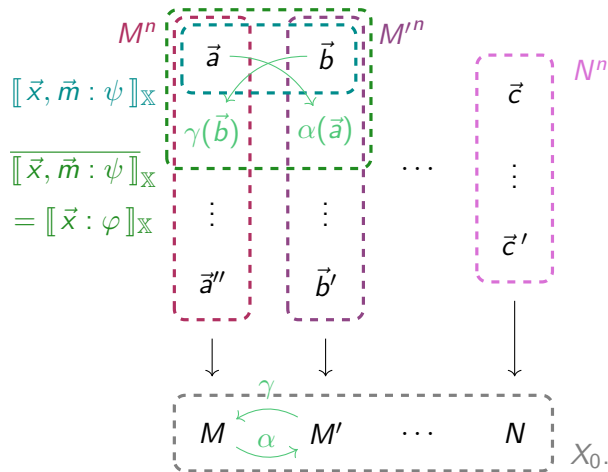
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Main Definition

Given a groupoid \mathbb{X} of \mathbb{T} -models and an indexing $\mathfrak{K} \rightarrow \mathbb{X}$,

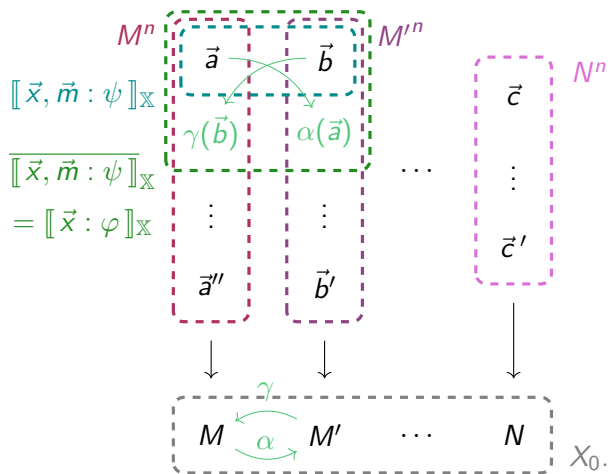
\mathbb{X} *eliminates parameters* if, for every ψ and \vec{m} , there exists some *geometric* formula φ such that

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Example

The automorphism group $\text{Aut}(\overline{\mathbb{Q}})$ eliminates parameters.

For each $a \in \overline{\mathbb{Q}}$,

$$\overline{\llbracket x = a \rrbracket_{\text{Aut}(\overline{\mathbb{Q}})}} = \llbracket x : p_a(x) = 0 \rrbracket_{\text{Aut}(\overline{\mathbb{Q}})},$$

where p_a is the minimal polynomial for a .

Classification result

Main Theorem (J.W.)

Let \mathbb{T} be a geometric theory and let $\mathbb{X} = (X_1 \rightrightarrows X_0)$ be a small groupoid of \mathbb{T} -models.

We can endow \mathbb{X} with the structure of an **open** topological groupoid for which

$$\mathbf{Sh}(\mathbb{X}) \simeq \mathcal{E}_{\mathbb{T}}$$

if and only if

(i) X_0 is a conservative set –

$$\llbracket \vec{x} : \varphi \rrbracket_{\mathbb{X}} = \llbracket \vec{x} : \chi \rrbracket_{\mathbb{X}} \implies \varphi \equiv_{\vec{x}}^{\mathbb{T}} \chi,$$

(ii) there is an indexing of \mathbb{X} by parameters \mathfrak{K} for which \mathbb{X} eliminates parameters –

$$\overline{\llbracket \vec{x}, \vec{m} : \psi \rrbracket_{\mathbb{X}}} = \llbracket \vec{x} : \varphi \rrbracket_{\mathbb{X}}.$$

Applications

Proposition (cf. Awodey–Forssell [1],[4], Butz–Moerdijk [2], Caramello [3])

(i) The groupoid of all \mathfrak{K} -indexed models eliminates parameters.

(ii) The groupoid of all \mathfrak{K} -enumerated –

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- (ii) The groupoid of all \mathfrak{K} -enumerated –
 every element is indexed by infinitely many parameters
 – models eliminates parameters.
- (iii) If \mathbb{T} is an atomic theory, then
 $\text{Aut}(M)$ eliminates parameters $\iff M$ is *ultrahomogeneous*,
 i.e. every finite partial isomorphism of M extends to a total isomorphism,

$$\begin{array}{ccc}
 \vec{n} & \xrightarrow{\sim} & \vec{n}' \\
 \downarrow & & \downarrow \\
 M & \dashrightarrow^{\sim} & M.
 \end{array}$$

Étale complete groupoids

Definition (Moerdijk [5])

Let $\mathbb{X} = (X_1 \rightrightarrows X_0)$ be a groupoid of \mathbb{T} -models.

We say that \mathbb{X} is *étale complete* if for each pair $M, N \in X_0$, every isomorphism $M \xrightarrow{\alpha} N$ is in X_1 .

The *étale completion* $\hat{\mathbb{X}}$ of \mathbb{X} is the étale complete groupoid with objects X_0 .

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Corollary (cf. Joyal–Tierney [6])

If \mathbb{X} eliminates parameters, then adding isomorphisms to \mathbb{X} preserves elimination of parameters.

Thus, for every open topological groupoid, there is an equivalence

$$\mathbf{Sh}(\mathbb{X}) \simeq \mathbf{Sh}(\hat{\mathbb{X}}).$$

Thank you for listening

The preprint:

On topological groupoids that represent theories, arXiv:2306.16331

Other references:

- [1] Awodey, S.; Forssell, H. First-order logical duality. *Ann. Pure Appl. Logic* 164 (2013), no. 3, 319–348.
- [2] Butz, C.; Moerdijk, I. Representing topoi by topological groupoids. *J. Pure Appl. Algebra* 130 (1998), no. 3, 223–235.
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- [6] Joyal, A.; Tierney, M. An extension of the Galois theory of Grothendieck. *Mem. Amer. Math. Soc.* 51 (1984), no. 309, v–71.