

LMI OPTIMIZATION WITH APPLICATIONS IN CONTROL

Didier HENRION

henrion@laas.fr

Belgian Graduate School on
Systems, Control, Optimization and Networks

Leuven - April and May 2010

Course outline

First part

- I.1. Technical background (linear algebra, numerical analysis)
- I.2. What is an LMI ? (historical survey, SDP)
- I.3. LMI duality (Lagrangian, multipliers)
- I.4. Convex LMI modelling (liftings and projections)
- I.5. Nonconvex LMI modelling (relaxations)
- I.6. LMI solvers (interfaces and algorithms)

Course outline

Second part

- II.1. State-space analysis methods
- II.2. State-space design methods
- II.3. Polynomial analysis methods
- II.4. Polynomial design methods

Course material

Convex optimization (including LMI):

- A. Ben-Tal, A. Nemirovskii. www.isye.gatech.edu/~nemirovs

Modern Convex Optimization. SIAM, 2001

- S. Boyd, L. Vandenberghe. www.stanford.edu/~boyd

Convex Optimization. CUP, 2005

LMI solvers and interfaces:

- J. Löfberg's YALMIP wiki

www.control.isy.liu.se/~johanl

LMI in control:

- C. Scherer, S. Weiland.

EECI graduate school on control